

# Safety Guarantees for Automated Vehicles

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# Motivation

## Set-based prediction of traffic participants

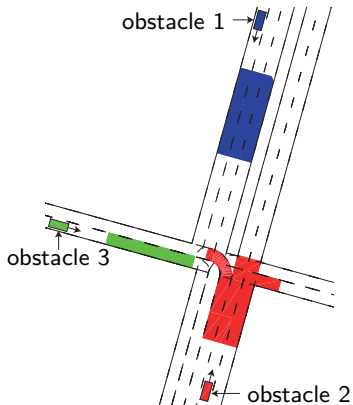


Figure: Predicted occupancies for  $t \in [1.5 \text{ s}, 2.0 \text{ s}]$ .

# Open Seminar Topics

- Occlusion
  - How can we consider what we cannot detect?
  - Your task: Literature review on the challenges through occlusion for automated vehicles
  
- Prediction of pedestrians
  - How can we efficiently and safely compute the future occupancy of pedestrians?
  - Your task: Literature review on prediction of pedestrians for automated vehicles
  
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